

NavDP4000 Series Dynamic Positioning Systems

NavDP 4000 Series – The Professional's Choice

Navis Engineering OY, founded in 1992, is one of the few world experts in dynamic positioning. Having supplied DP systems for more than 300 vessels in 10 years, Navis is recognized as a reliable provider of "turn-key" solutions for high quality Dynamic Positioning Systems.

High efficiency, a profound understanding of every customer's needs as well as global market trends, combined with the outstanding quality, reliability and simplicity of the systems – this is what our company stands for.

Sharing experience - Navis Engineering is a member of



The NavDP 4000 Series is a new generation of Navis Dynamic Positioning Systems combining the best qualities of the previous system, the Navis IVCS Series, with the latest achievements in technology and recent design ideas gained from experienced users' feedback, recent Class rules changes and market trends.

Applications

The Navis NavDP4000 series system is fully flexible in configuration design and can be supplied as a stand-alone or integrated solution tailored to the specific needs of every customer, be it a high-end newbuilding or a retrofit vessel.

Having a lot of retrofit projects in our reference list, we always find the optimal solution to ensure the best results in any given situation.

The modular architecture of the Navis NavDP 4000 Series allows for integration with various types of propulsion/thruster and power management systems. The sensors and reference system are selected according to Class rules and vessel mission.

Typical applications for the NavDP 4000 series include:

- Offshore supply vessels
- Crew boats
- Anchor Handling Tug Supply vessels
- Diving Support Vessels
- Heavy Lift Semi-Submersible Vessels
- Oil and Gas shuttle tankers
- Dredgers
- Cruise ships and mega-yachts
- Hydrographic survey vessels
- Buoy tenders
- Cable layers







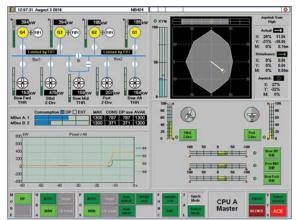


NavDP4000 Series Highlights

This section provides an overview of selected features of the Navis NavDP 4000 Series design. Since the functionality and system design of DP systems is largely dictated by Class requirements, this document is not intended to list all the features available in our system

ADVANCED ERGONOMIC DESIGN OF WORKSTATIONS

Alongside the standard NavDP 4000 Series workstation console, we can offer our new integrated DP control chair solution for high-end newbuildings with the set of functionality fitted to the operator's needs. Both solutions have been designed following Det Norske Veritas (DNV) rules and using experienced DP operators' feedback to ensure a friendly environment for the operator as well as for the service staff.



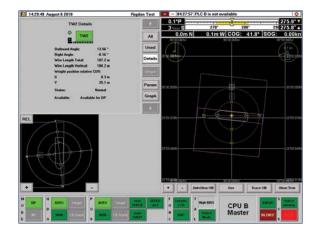
USER INTERFACE DESIGN CONCEPT

The user interface of the Navis NavDP 4000 Series has been developed in cooperation with experienced DP operators and ergonomic experts. Priorities have been given to clear and unambiguous presentation of information, timely error-free access to functions, and simplicity.

Although the system is based on the Windows operating system, the design of the new user interface does NOT accept standard "Windows-like" controls. Instead it uses "device-like" controls.

The combination of the high quality marine touch screen and the new generation DP control panel equipped with a highresolution color display has as few as a dozen of buttons and controls, providing a unique intuitive and self explanatory user interface.

Voice alarms and a messaging function help to maintain a high level of awareness in any situation.



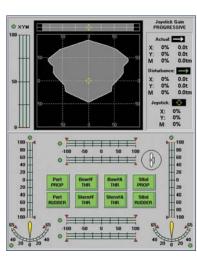
THRUST ABILITY DIAGRAM

Navis Engineering has developed unique functionality in Dynamic Positioning Systems.

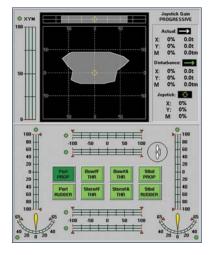
For a particular thruster configuration, the Thrust Ability Diagram shows in real time all possible combinations of control forces in the surge and sway axes for a given value of the rotational control moment and thruster availability and/or allowed power load.

Since each pair of forces can be considered as a vector, the diagram is a bounded set on a plane where every point corresponds to a particular combination of control forces achievable.

This set of forces depends on how much is demanded on the rotational moment. Should any change happen to parameters or conditions, the diagram is automatically updated on the screen.



All thrusters active



Port Engine Lost

If the desired force vector goes beyond the boundary of the set, the actual force vector is on the boundary, and the system tries to minimize the difference.

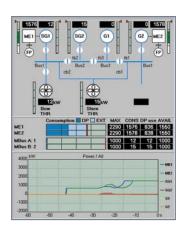
POWER MONITORING AND BLACKOUT PREVENTION

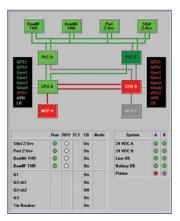
Information from the Power Management System and Thruster System is continuously received by the NavDP4000, including the load on each generator and thruster, the way the thrusters and generators are connected to the power buses, and the way the power buses are connected to each other.

The NavDP4000 monitors the power load to avoid blackouts. In case a blackout might occur, the NavDP4000 computes new demands on the force and moment, which satisfy the power limitations and ensure proper operation for each generator, and assign a new thrust to each thruster, so that the effect on the position and heading control is minimized. The Power Management Function is active in all modes.

SYSTEM MONITORING

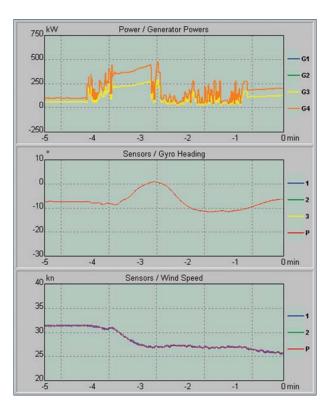
The system constantly controls the state of its components (PLCs, computers, buses, etc.), sensors, thrusters, generators and power circuits in real time. The respective information is also available for the operator in the form of messages and also as an easy-to-understand diagram, which can be displayed on the screen on request. The diagram uses different colors to indicate the state of the components and the connections between them. If a component or a connection changes its state (i.e. becomes active or inactive or fails), the color with which the component is displayed also changes.





TREND VIEW

In the NavDP4000's Trend View window the operator is able to trace the system performance history for three different sets of parameters at a time.



Trend View Window

MULTI-TARGET FOLLOWING

The Target Following mode is used to follow a target or to position the vessel within a pre-defined range around the target selected. The NavDP4000 provides both single- and multi-target following modes. In the Multi-Target mode the data on the range of the multitarget group is received from the first target, while the second target provides the information about the group bearing.

CONSEQUENCE ANALYSIS

For DP2 Class vessels, the Consequence Analysis function makes it possible to determine whether the vessel is able to maintain its position in the case of a worst-case failure, the most typical of which are thruster failure, generator failure and the circuit breaker/tie breaker failure.

Possible consequence prediction is based on the actual weather conditions, the performance of the enabled thrusters and the power plant (generators, circuit breakers, tie breakers) status.

Fransponders	Raw Da	ta	Xg, m	Yg, m	4
HPB1	Bearing:				
(1) 11	Range:				
	Depth:				All
HPR1	Bearing:				
4 04	Range:				Used
	Depth:				
HPR1	Bearing:				
42 42	Range:			******	Multi-
	Depth:				Target
HPR2	Bearing:	74.5*REL			
22 22	Range:	2132.0 m	260435.7	41441.2	-
	Depth:	100.0 m			Param
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Multi-Target Following Mode

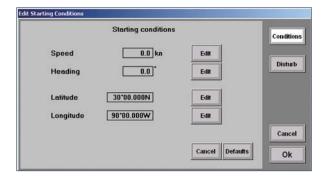
X: Y:		Avg	F U Present System	Limits
Y:	7.3t	6.5t	Bow#1 Thruster	100 %
	-24.1t	-21.2t	Bow#2 Thruster	100 %
M:	-904.1t	-761.2t	Port Z-Drive	100 %
	,	,	Stbd Z-Drive	100 %
Power	Avail kW	Used kW	Generator G1	100 %
Bus A	3140	1890	Generator G2	100 %
Bus B	0.1.0	1179	Generator G3	100 %
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Pre	esent Syste nerator G1 nerator G2	m lost lost	Setpoint Heading 0	×

SIMULATOR MODE

Each Navis' DP system is delivered with a built-in Simulation Mode functionality that provides simulations for operator training, also making it possible to analyze the vessel's performance changes in different environmental conditions.

Simulations are performed at the DP system control station (console). No additional equipment is required. The simulation mode can only be used when the system is not in use for DP operations.

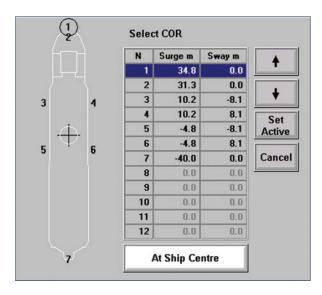
Starting the simulation session, the operator can set the initial conditions (vessel initial speed, heading, latitude and longitude). The environmental conditions (wind and current speed and direction, wave height and direction, Water depth settings) can also be set.



Similator Mode Screen

CENTER OF ROTATION

For different tasks required during operation of special application vessels, the NavDP4000 provides the functionality of setting different centers of rotation. It can be located either in the ship's center, in the bow or stern, or in any other location manually set by the operator. Whatever COR is used for operation, the system will guarantee the ultimate positioning precision.



Center of Rotation Screen



BLACK BOX OPTION

The Navis DP features an advanced option for recording, storage and playback of data related to DP operation.

If installed in addition to the conventional Alarm and Event printer required by Class, it insures precise recording of:

- Ship sensor data available for DP
- Position reference system data
- Results of filtering processes
- Thruster commands and response
- PMS information
- System faults
- Operator actions
- Other relevant data

Though recording devices for ship operations are not yet required by IMO or Class, they help the ship-owner in assessment of DP-casualty cases.

They store the data in in a protected capsule on the removable HDD of a computer.

AUTOPILOT CONTROL MODE

The NavDP 4000 Series is equipped with a built-in fully functional autopilot, which has been type-approved by DNV as a Heading Control System. The Autopilot Mode is used for heading control when the vessel is moving forward. Since it is approved for navigation, it can be used instead of a separate conventional Heading Control System.

The compact panel of the Navis AP4000 DNV-approved autopilot can optionally be used in the forward navigation console as a remote control station for the autopilot if an aft-view Independent Joystick System is installed. Alternatively, a forward-view Independent Joystick System may be used to control the autopilot if particular Class rules permit such a bridge arrangement.

This solution complies with the following regulations:

- IMO Resolution MCS.64 (67), annex 3 Performance standards for heading control systems
- IMO Resolution A342 (IX) Recommendation on performance standards for automatic pilots
- IEC 60945 Maritime Navigation and radiocommunication equipment and systems – General requirements – Methods of testing and required test results
- ISO 11674 Ships and marine technology Heading Control Systems
- IEC 61162-1:2000(E) Maritime navigation and radio communication equipment and system
 Digital interfaces – Part 1: Single talker and multiple listeners – Second edition 2000-07

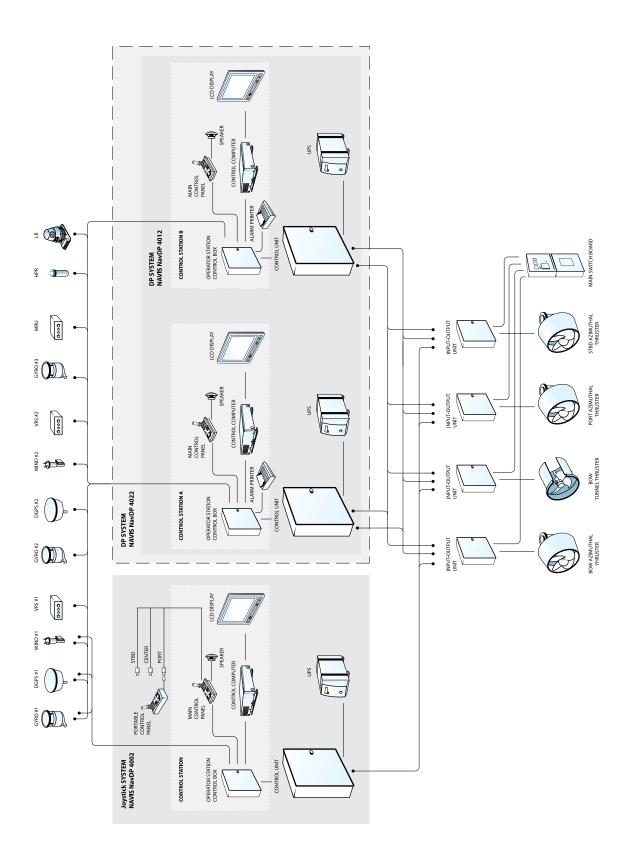
< 23 3.9knt 0 TRU Wind Dir: 0 TRU 2 Wind SPD: 0.0 m/s б 65 **34**.5° ROT ROT: S ROT SOG 250.5° 250.5 59 9-9 9 kr 59.9 99 kr







The range of NavDP4000 configurations secures compliance with all the functional and redundancy requirements set by IMO, DNV, BV, LRS, CCS, IRS and RMRS for DP systems of Classes 1-3.



Turn-Key Solutions



Working in close cooperation with all the major Classification Societies (DNV, ABS, Lloyd's Register, BV), our project team ensures that every system we supply will receive optimum Class approval. The Navis Group provides reliable follow up within a whole project period, which ensures that a customer gets a complete turn-key solution.

We provide:

- Initial ship inspection
- Project services
- Class approval
- Logistic support
- Commissioning of a system
- Sea Trials
- Crew Training

The use of extensive testing allows us to reveal all possible problems and errors which may occur during installation and commissioning. This minimizes the amount of time and effort spent during installation, reducing costs as well. Testing is performed using high-precision, realistic models of the sea environment and the motion of the vessel.







CREW TRAINING

Navis Engineering provides a multi-level solution for training. It ranges from the stand-by simulator mode available in every DP we supply up to the full-scale DP Training class simulator, Navis-MTC DPS Trainer C4/2, used for DP operator training in the training centers accredited by the Nautical Institute of London, as well as for crew briefing in ship-owners' offices.

At present, Navis' DP simulators are installed in 20 Nautical Institute accredited training centers around the world, either as part of the full-mission bridge simulator or as an independent DP training facility.

Service and Support

Wherever you are on the globe, Navis Engineering offers you a comprehensive package of technical support 24/7 x 365 days a year. The combination of extensive built-in diagnostics, hot-line support, a network of service agents with Navis Engineering certified field service engineers, and our service centers with senior engineers ready to fly to your vessel within 24 hours, no matter where it is located, ensures a timely response to any technical problem.

The Navis Service Center in Helsinki provides prompt of service agents and partners to accomplish what needs to be done.



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